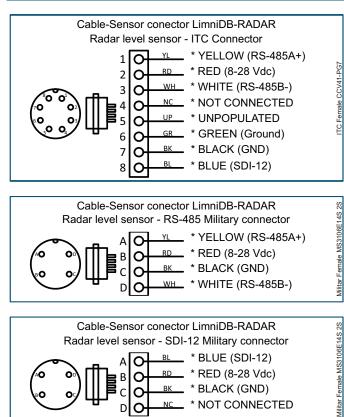
## LimniDB-RADAR Instruction sheet

#### **Radar distance sensor (limnimeter)**



### WIRING DIAGRAM



NOT CONNECTED

#### **OPERATION**

| List of common commands via SDI-12 |                             |
|------------------------------------|-----------------------------|
| Command                            | Function                    |
| a!                                 | Acknowledge active          |
| aAb!                               | Change address (default: 0) |
| ?!                                 | Check address               |
| aM!                                | Start measurement           |
| aD0!                               | Send data                   |
| aM1!                               | Additional measurements     |
|                                    |                             |

Order of information sent via SDI-12

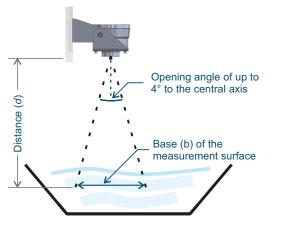
#### Order Variable Unit\* Distance (level 1st cm 2nd X-axis Degrees 3rd Y-axis Degrees 4th Internal temperature °C Internal humidity % RH 5th \*Standard unit; Other units available.

### Serial interface via RS-485 Address: 1 (default) **Configuration:** 8-N-1 Transmission rate: 9600

# decoding the environment MOUNTING

dualBA





The sensor has a beam angle of up to 4° to the central axis, which should be taken into account during installation and the maximum distance (d) to be measured. The diameter of the base (b) of the measurement surface must be calculated to ensure there is no interference during the measurement:

 $b = d \times tan (radius \times 2)$ 

For exemple:

b = 35 meters x tan(8°), then: b = 4,92 meters